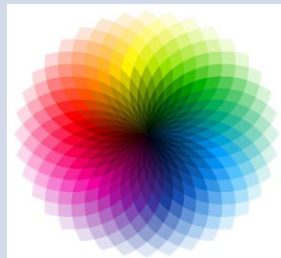




# Learning latent functions for causal discovery

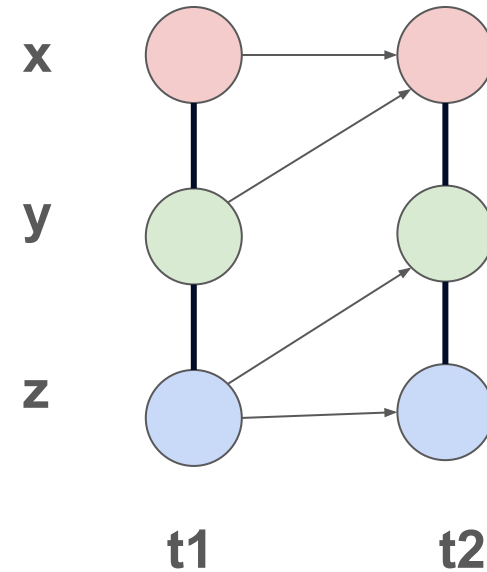
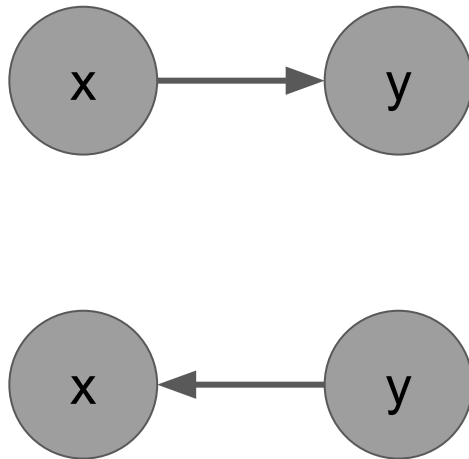
*.Machine Learning: Science and Technology IOP Science 2023*

**Emiliano Diaz Salas Porras, Gherardo Varando, J. Emmanuel Johnson, Gustau Camps-Valls**



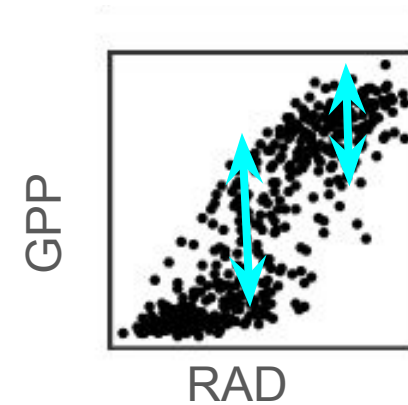
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**Universitat de València**

A method to “plug-in” after the Markov equivalence class has been estimated

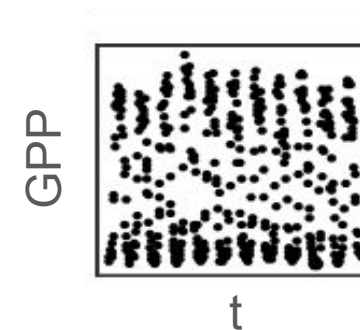
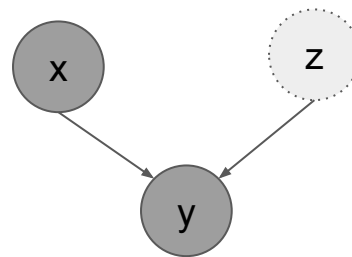


## Non-additive data important for Earth system science

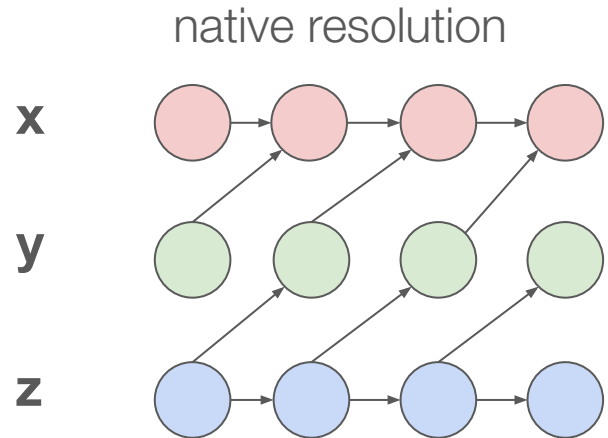
1. weak form of non causal sufficiency



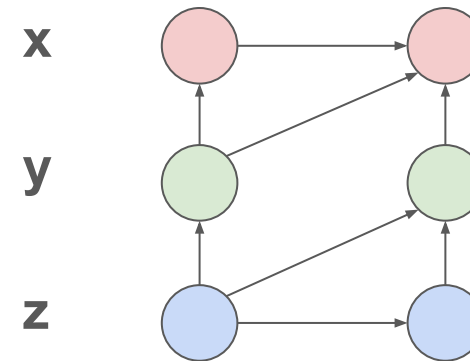
2. can generate structured data e.g. spatial, temporal



- “Instantaneous” relationships often occur in practice due to systems observed at lower resolution than the fundamental mechanisms.
- In this case additional assumptions necessary to identify the causal structure.

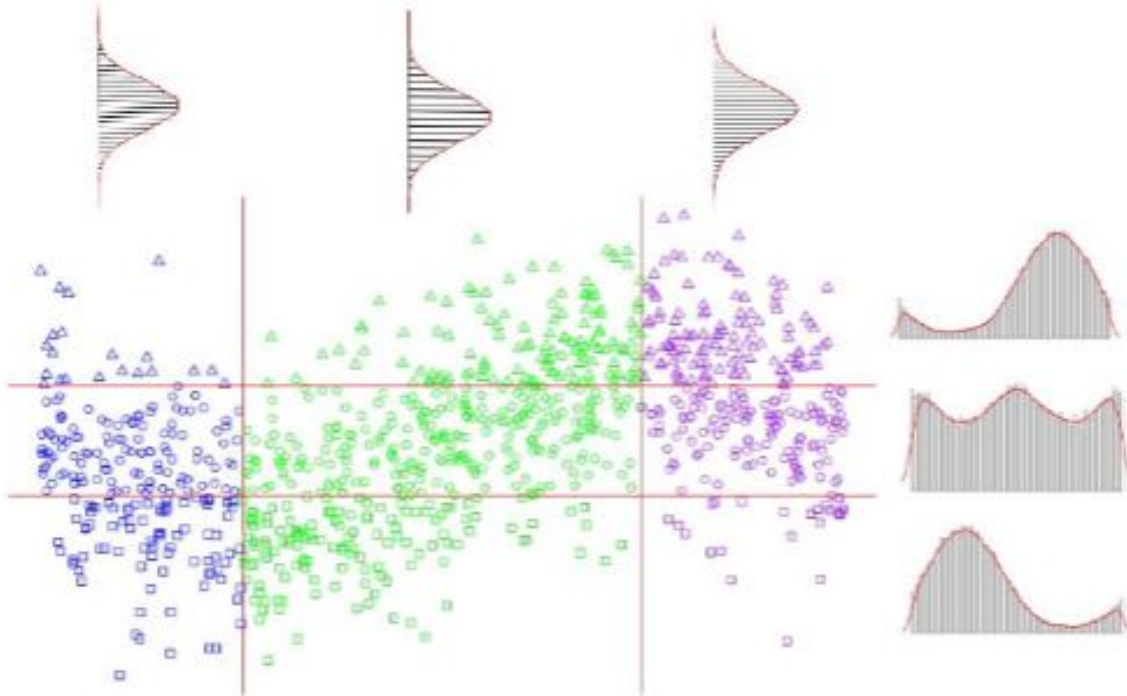


aggregated low resolution



## Examples

- Daily ERA5 data
- Weekly satellite data
- harmonization of different products to lower temporal resolution



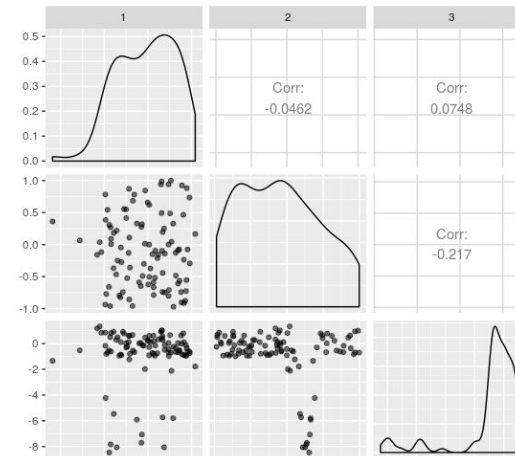
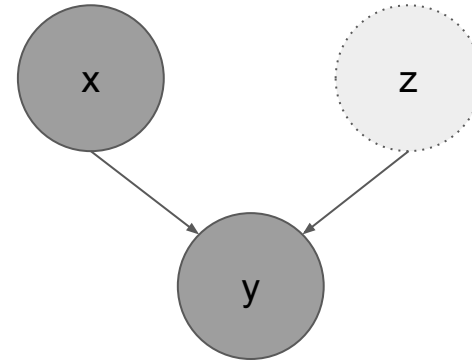
To identify causal structure when instantaneous relationships exist we need extra assumption.

- modularity assumption
- ie no info about  $p(y|x)$  in  $p(x)$

# Taking a step back: modeling the inducing FCM

$$y := f(x, z)$$

Latent Noise approach



conditional pdf approach

For a data generating mechanism  $y = f(x, z)$  we make the following assumptions, following (Stegle, et al 2010)

1. Deterministic process
2. Exogenous noise  $z$
3. Gaussian noise  $z$
4. Algorithmic independence

$$L(\mathcal{Z}) = \ln(nHSIC(\mathcal{X}_a, \mathcal{R}_{x \rightarrow y})) + \zeta \ln(MSE(\mathcal{R}_{x \rightarrow y})) \\ + \eta \ln(nHSIC(\mathcal{X}, \mathcal{Z})) + \nu \ln(SMMD_{\mathcal{N}}^2(\mathcal{Z}))$$

where:

$$\mathcal{X}_a := \{(x_i, z_i)\}_{i=1}^n$$

$$\mathcal{R}_{x \rightarrow y} := \{y_i - f(x_i, z_i)\}_{i=1}^n$$

$$\hat{y} = f(x, z) = \sum_{i=1}^n \alpha_i k((x, z), (x_i, z_i)) \in \mathcal{H}_{xz}$$

$$\boldsymbol{\alpha} = (K_{xz} + n\lambda I)^{-1} \mathbf{y}$$

Deterministic process



$$L(\mathcal{Z}) = \ln(nHSIC(\mathcal{X}_a, \mathcal{R}_{x \rightarrow y})) + \zeta \ln(MSE(\mathcal{R}_{x \rightarrow y})) \\ + \eta \ln(nHSIC(\mathcal{X}, \mathcal{Z})) + \nu \ln(SMMD_{\mathcal{N}}^2(\mathcal{Z}))$$

where:

$$\mathcal{X}_a := \{(x_i, z_i)\}_{i=1}^n$$

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$$\boldsymbol{\alpha} = (K_{xz} + n\lambda I)^{-1} \mathbf{y}$$

Exogenous noise

$$L(\mathcal{Z}) = \ln(nHSIC(\mathcal{X}_a, \mathcal{R}_{x \rightarrow y})) + \zeta \ln(MSE(\mathcal{R}_{x \rightarrow y})) \\ + \eta \ln(nHSIC(\mathcal{X}, \mathcal{Z})) + \nu \ln(SMMD_{\mathcal{N}}^2(\mathcal{Z}))$$

where:

$$\mathcal{X}_a := \{(x_i, z_i)\}_{i=1}^n$$

$$\mathcal{R}_{x \rightarrow y} := \{y_i - f(x_i, z_i)\}_{i=1}^n$$

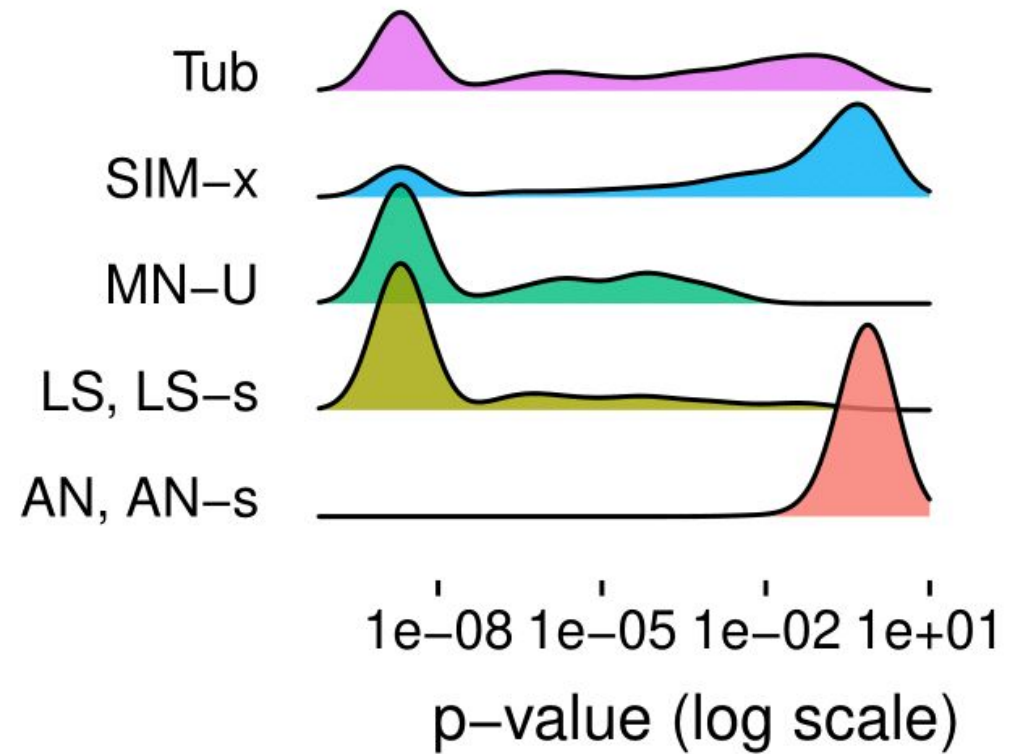
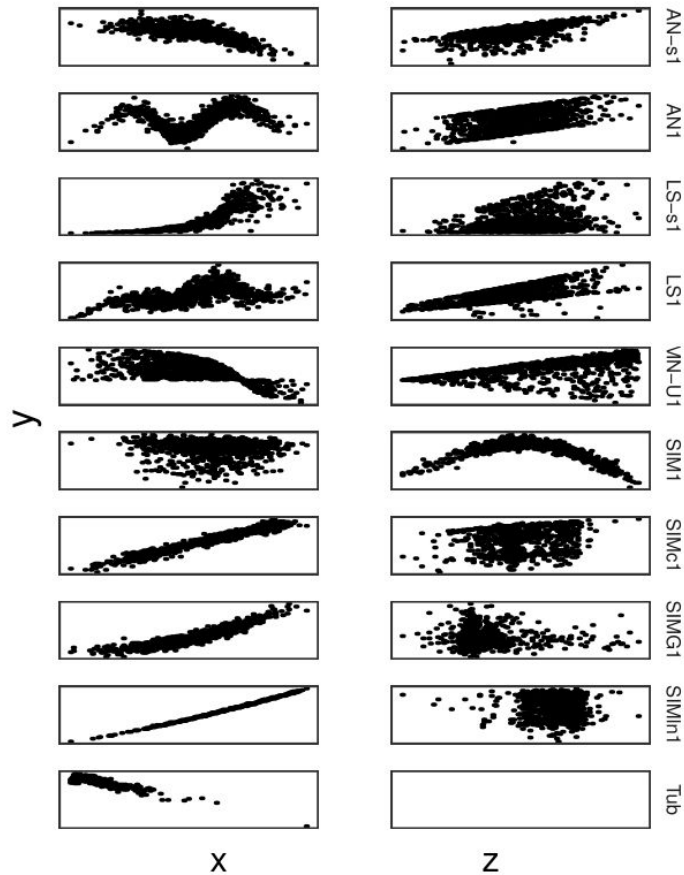
$$\hat{y} = f(x, z) = \sum_{i=1}^n \alpha_i k((x, z), (x_i, z_i)) \in \mathcal{H}_{xz}$$

$$\boldsymbol{\alpha} = (K_{xz} + n\lambda I)^{-1} \mathbf{y}$$

Gaussian noise

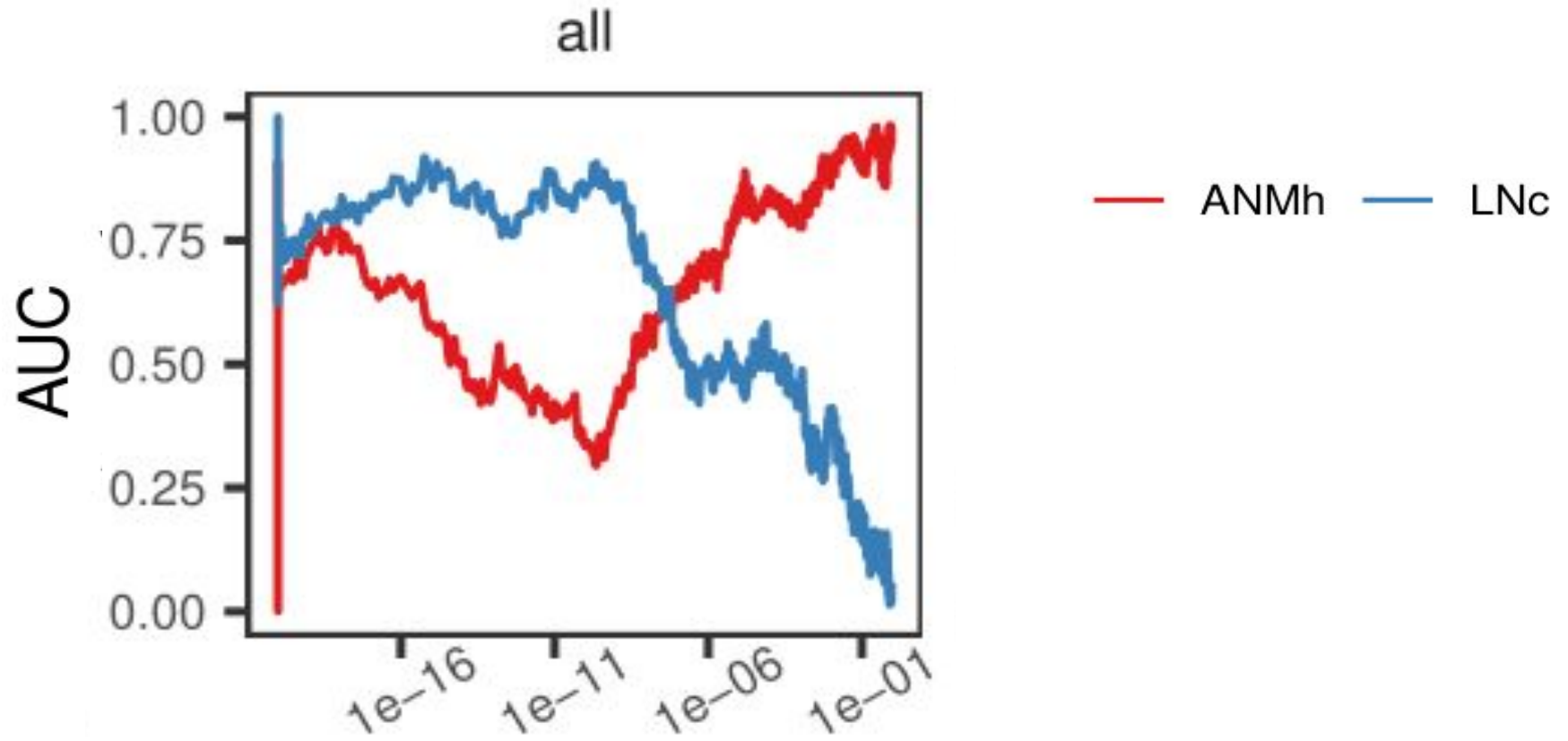
### Advantages

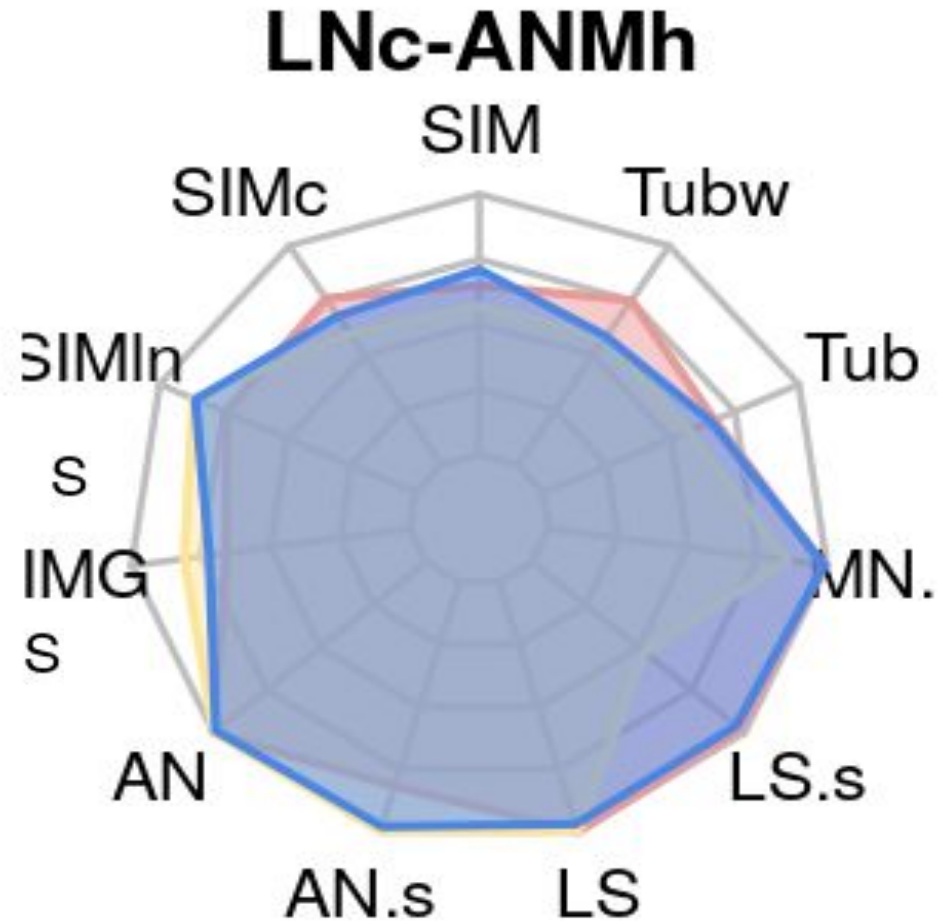
- Rank relative importance of assumptions
- Relaxing determinism assumption: use non-additivity as causal signal:
  - model misspecification (anti causal direction)
  - estimation error (both directions)
  - asymmetry assumption: model misspecification generates more non-additivity

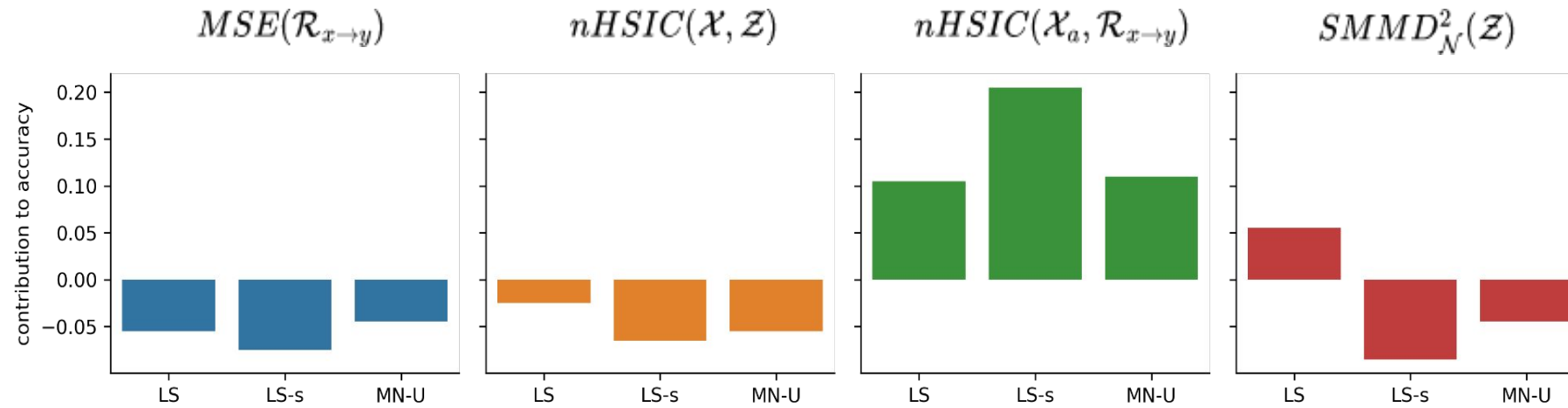


$$S = \min\{nHSIC(\mathcal{X}, \mathcal{R}_{x \rightarrow y}), nHSIC(\mathcal{Y}, \mathcal{R}_{y \rightarrow x})\}$$

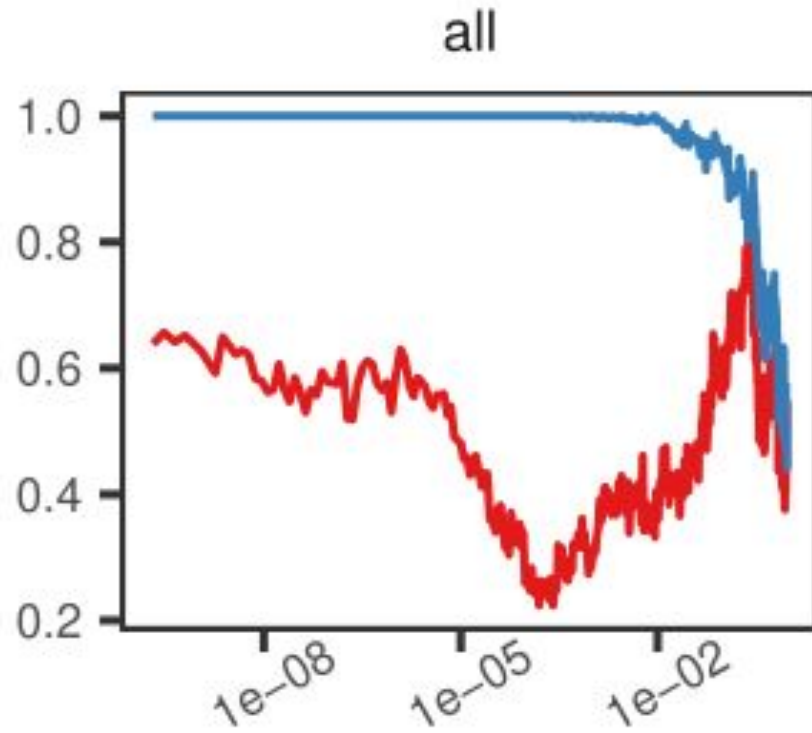
## LNc method's accuracy improves with non-additivity





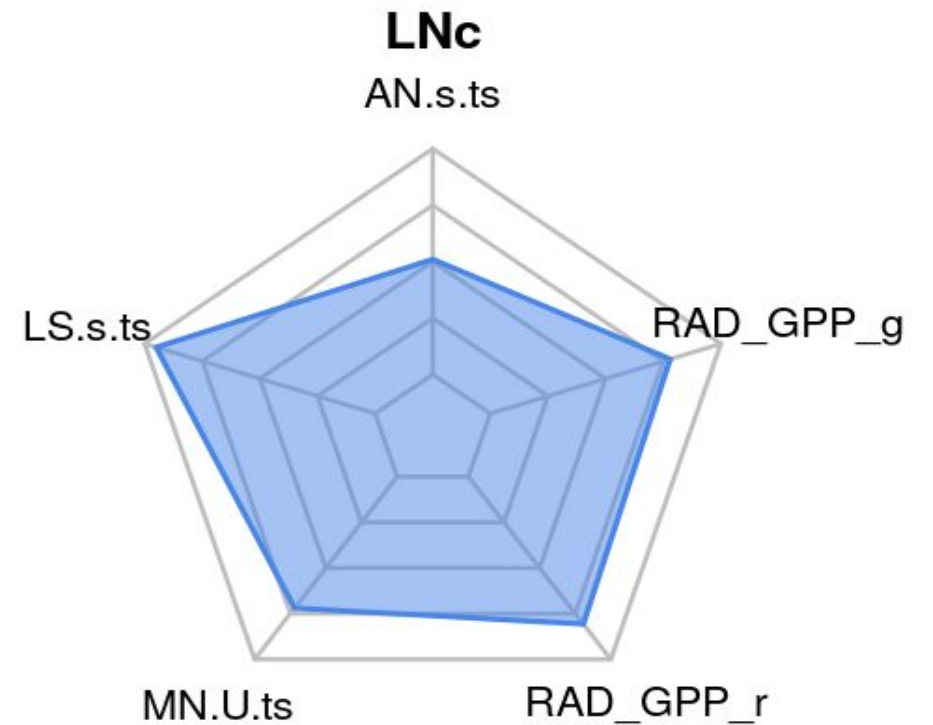


- Additive residual assumption only one that needs to be implemented strictly.



p-value

— LNC-ak-ts — LNC-ts





- Generative approach is advantageous for extending to spatio-temporal data.
- Generative LNc method including extension to time series and an additivity hypothesis test.

- Time series extension only applies when there is no self-dependence in effect variable
- Only suitable for cases where confounding is ruled out

- When causal discovery is applied to time series at an aggregated scale instantaneous effects very common: asymmetry methods suitable.
- A soft/weak form of non-causal sufficiency can be responsible for non-additive data: need asymmetry methods suited to this setting. Non causal sufficiency very common in Earth system science.
- Can be used to complement other causal discovery algorithms that don't make ICM assumption and can't fully identify causal structure when "instantaneous" relationships occur.



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